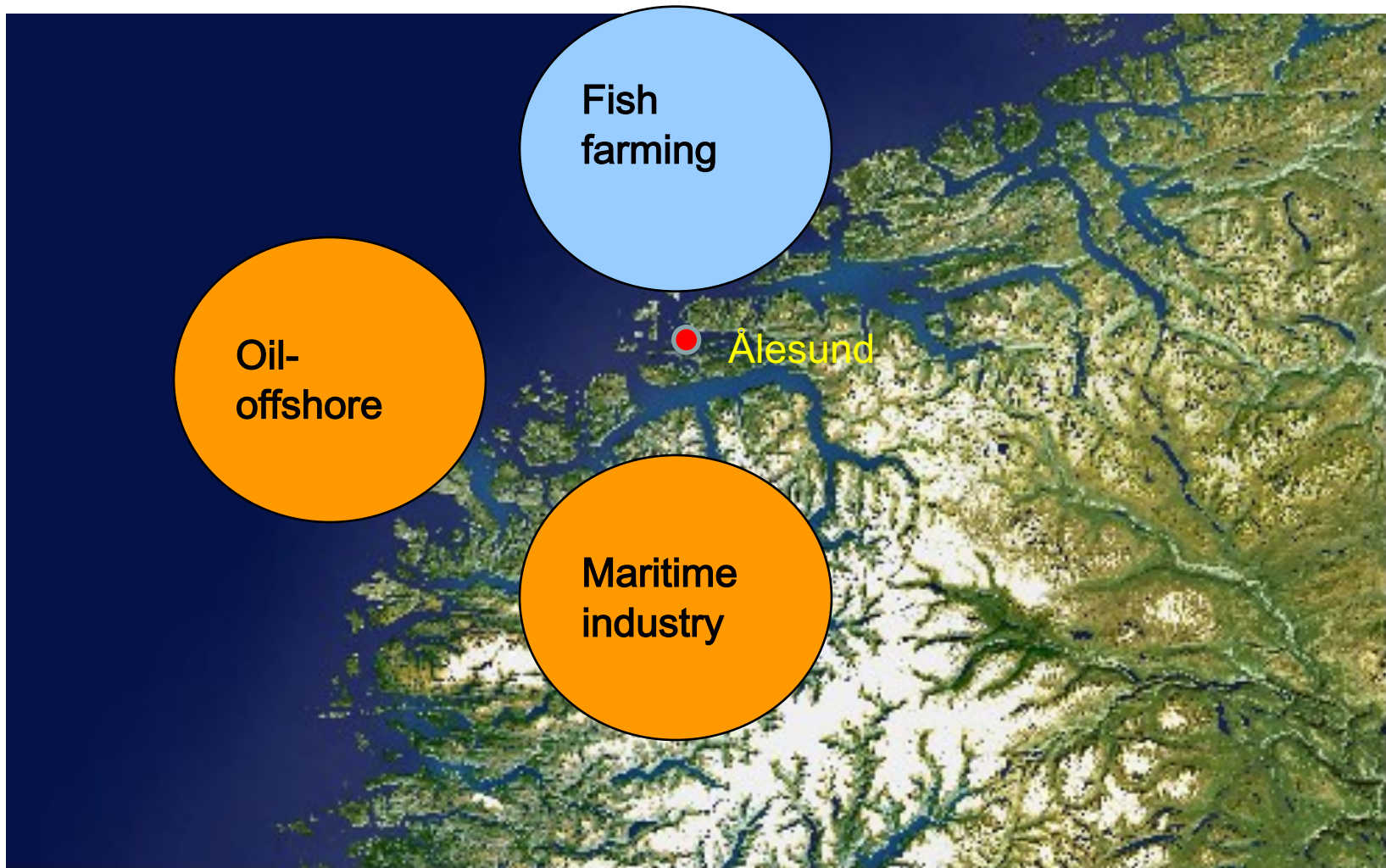


Multi-Agents in Virtual Regional landscapes

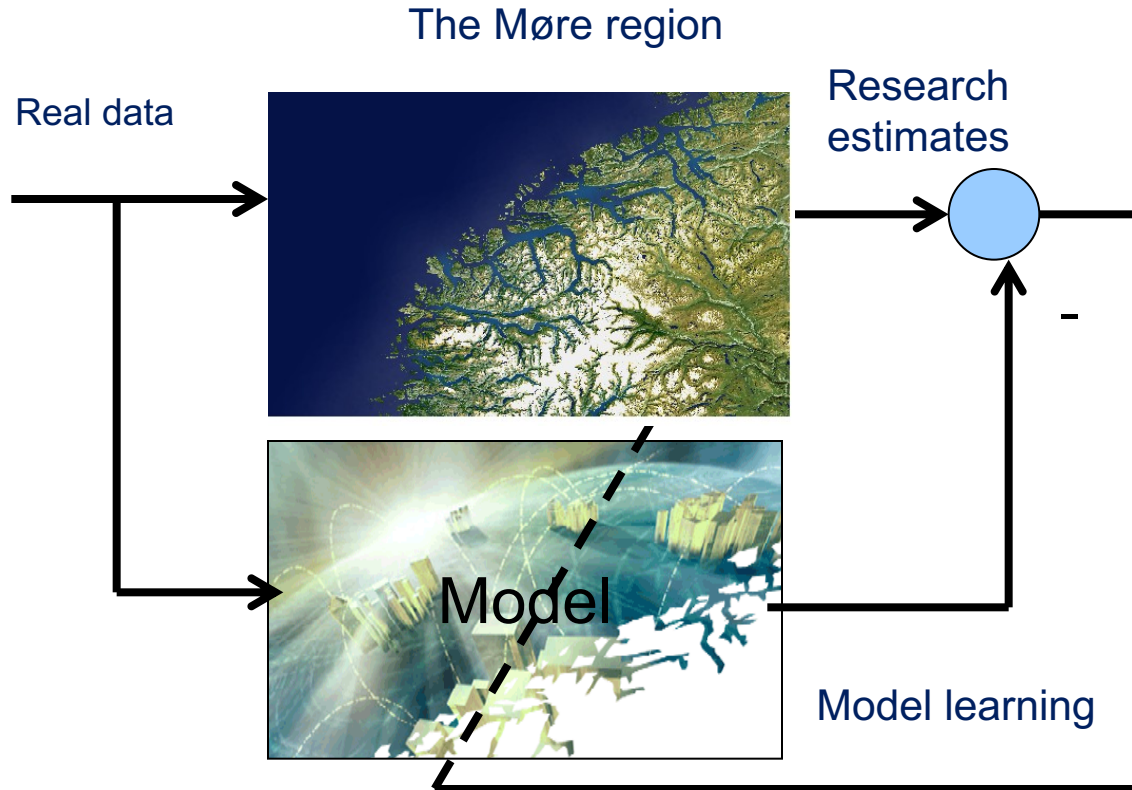
Prof. Harald Yndestad



The More Region in Norway



The Virtual Møre



The goal

1. Simulation and visualization and 3D maps as a research tool
2. Adaptive models for simulating og visualisering

The Ålesund city



Simple roads and houses



08.04.12

S&V/HY

The Virtual Ålesund

Nice houses in the city



Image NASA
Image © 2008 TerraMetrics
Image © 2008 DigitalGlobe

©2008 Google™

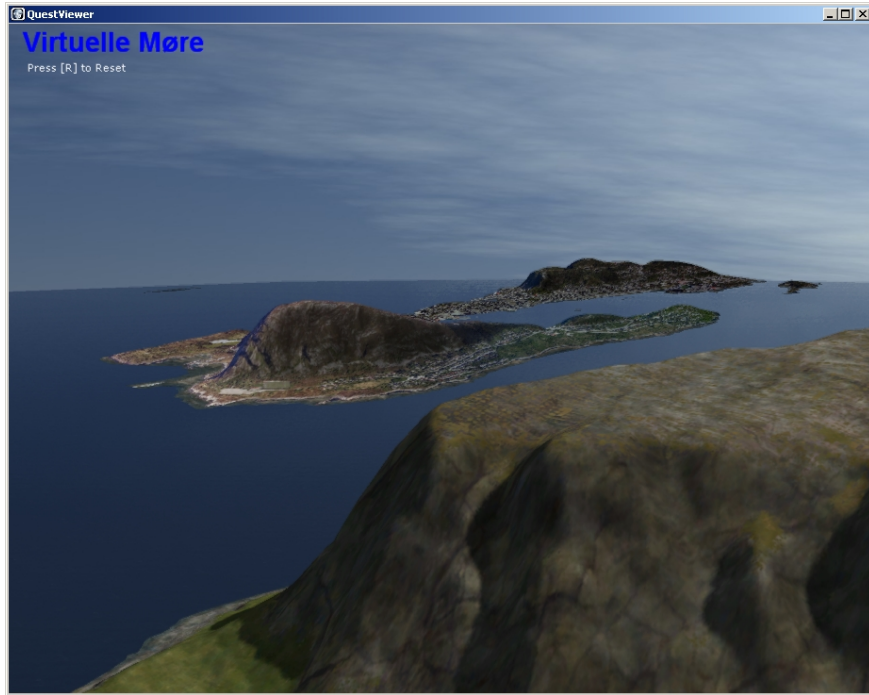
62°28'19.91" N 6°14'06.90" E

elev 6 m

Eye alt 83 m

The Virtual Ålesund region

Nice sea and nice mountains



15 x 15 km model



Introduceing a game engine

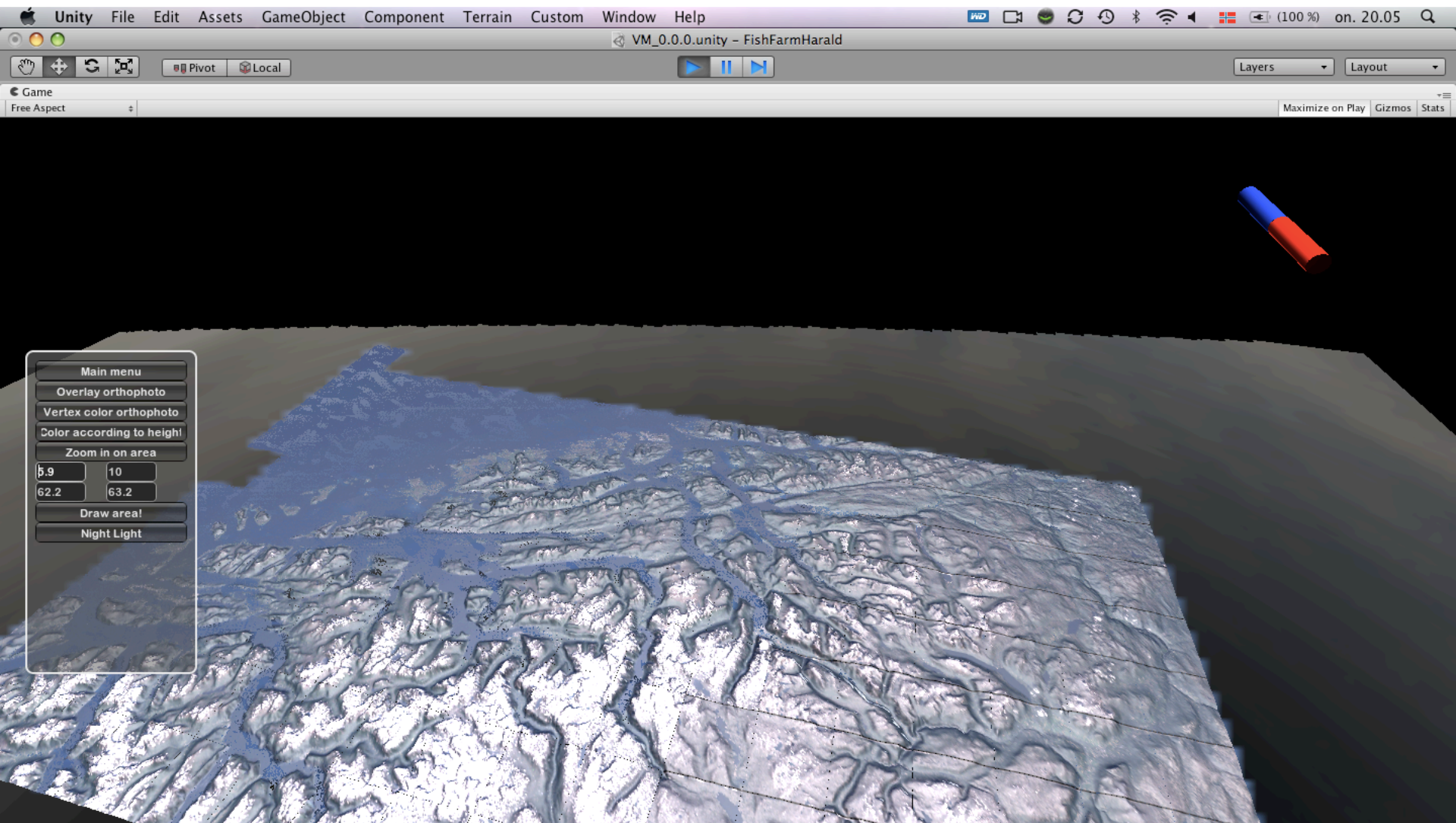
The beginning of large terrains

The beginning of visual agents on 3D terrains

The Virtual Møre region

The Landscape: GPS based 3D map

GPS-basert: +/- 10 cm



Simulation paradigm transform

From system dynamics, to individual dynamics

To a sum of individual models, based on free will



Virtual More as a generic concept:

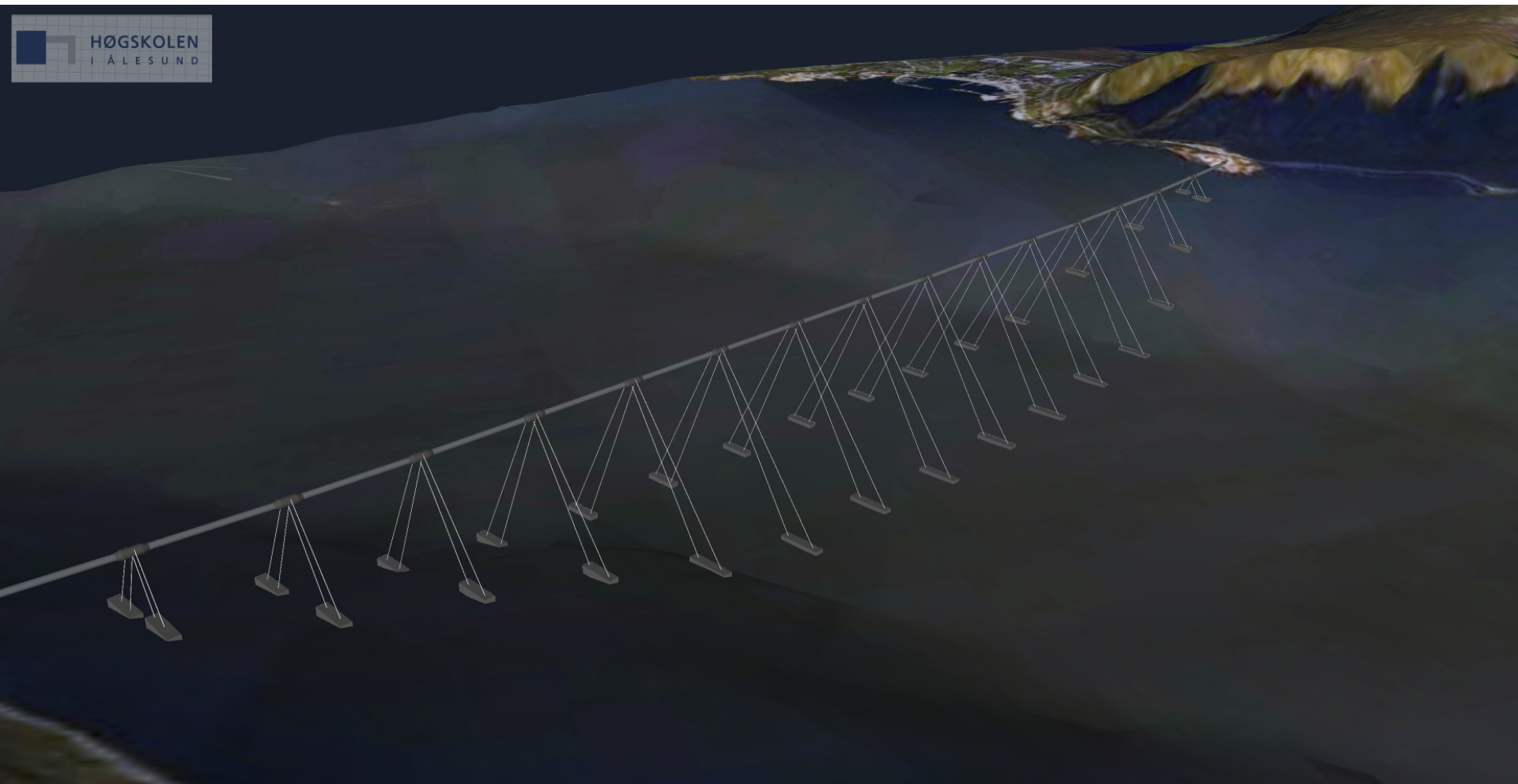
- 1 Everything is Agent or landscapes
- 2 Adaptive Agents in landscapes
- 3 Social agents learning
- 4 Evolution agents learning
- 5 Time variant landscapes
- 6 Abstract landscapes as cost functions
- 7 Complex systems dynamics
- 8 Systems of systems

Needs a generic concept

Car agents in action

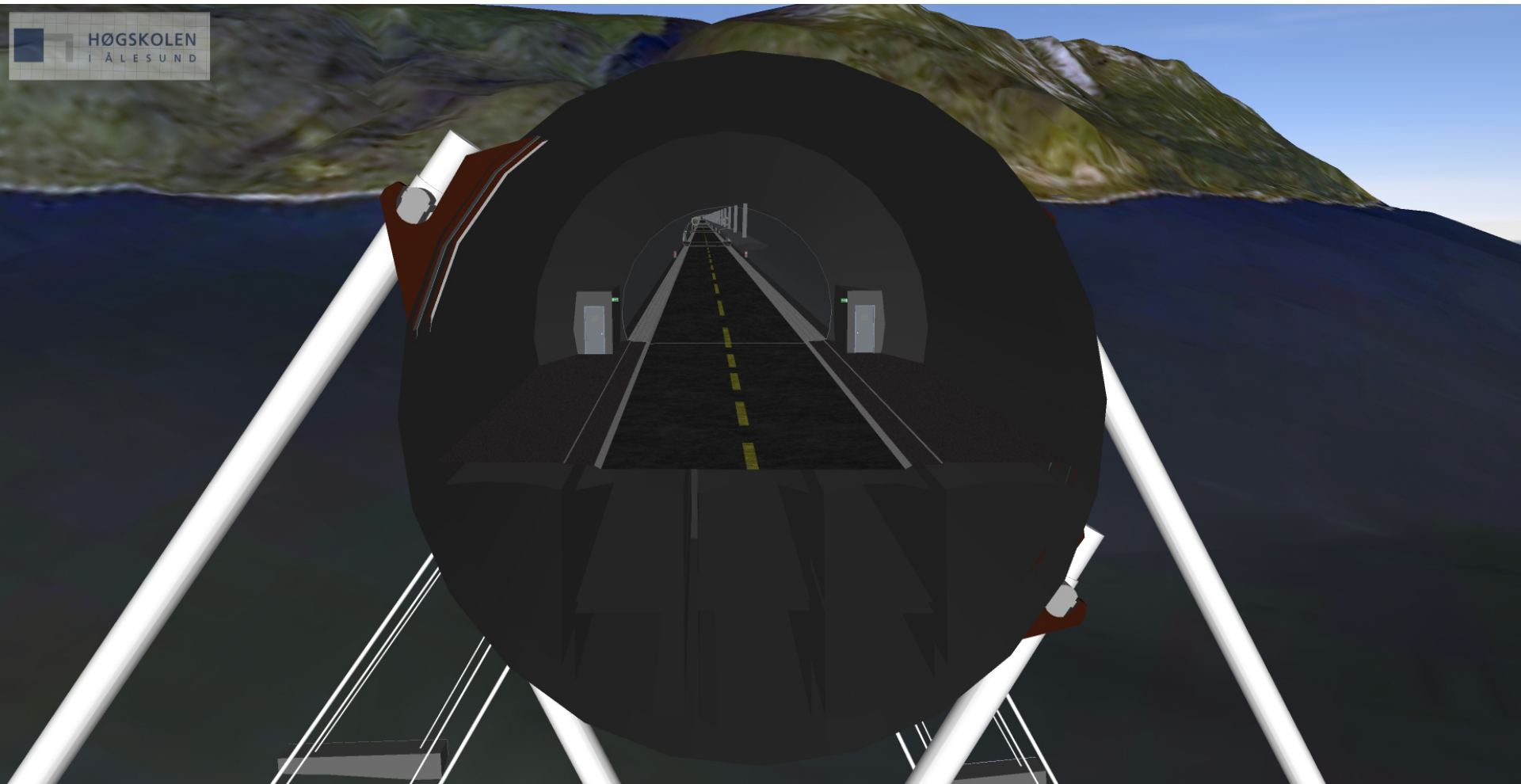
A car agent crossing an Norwegian fjord in a virtual tube tunnel

Camera on care agents, moving in a tube tunnel



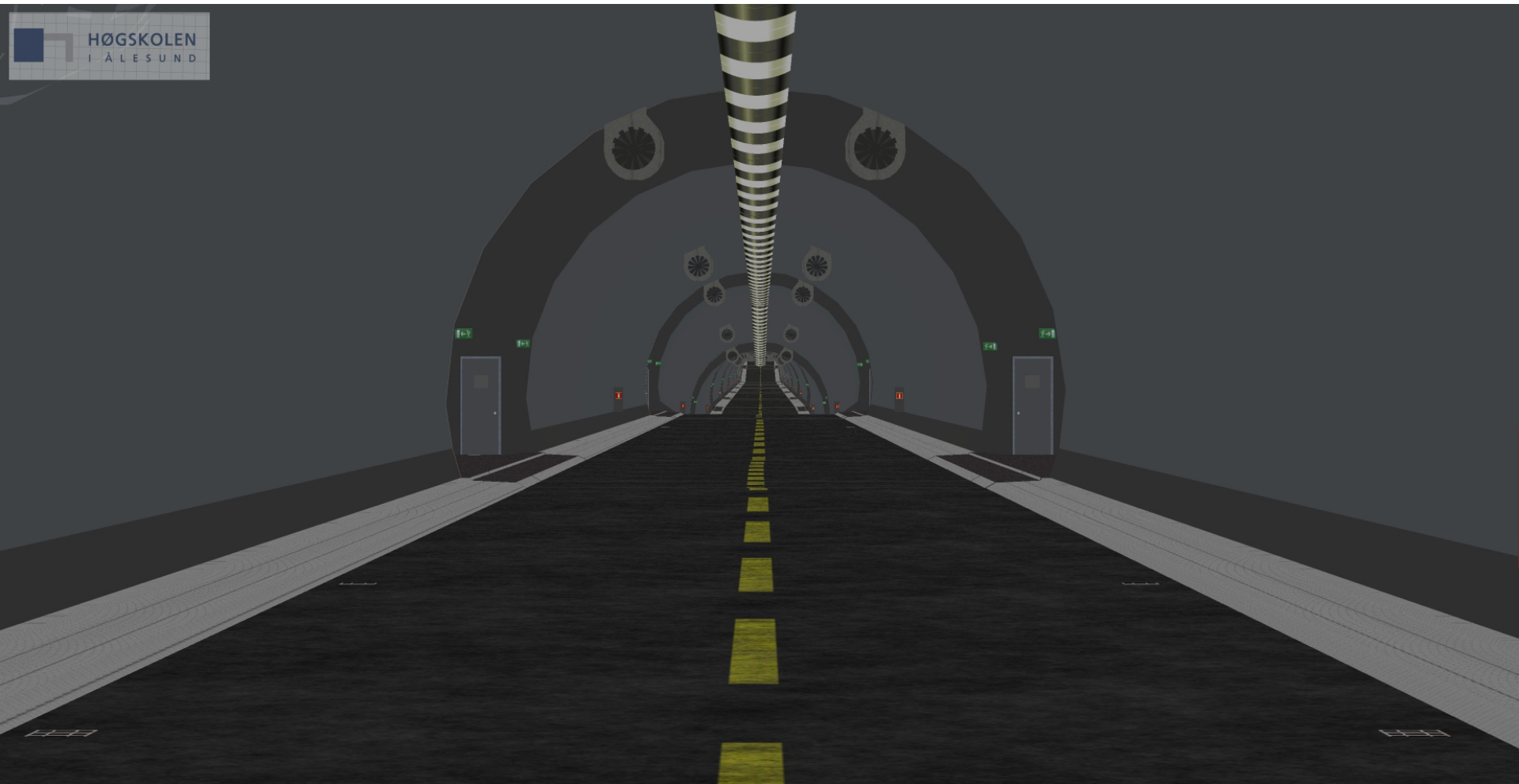
Car agents in a tube tunnel

A car as and agent, carries a camera



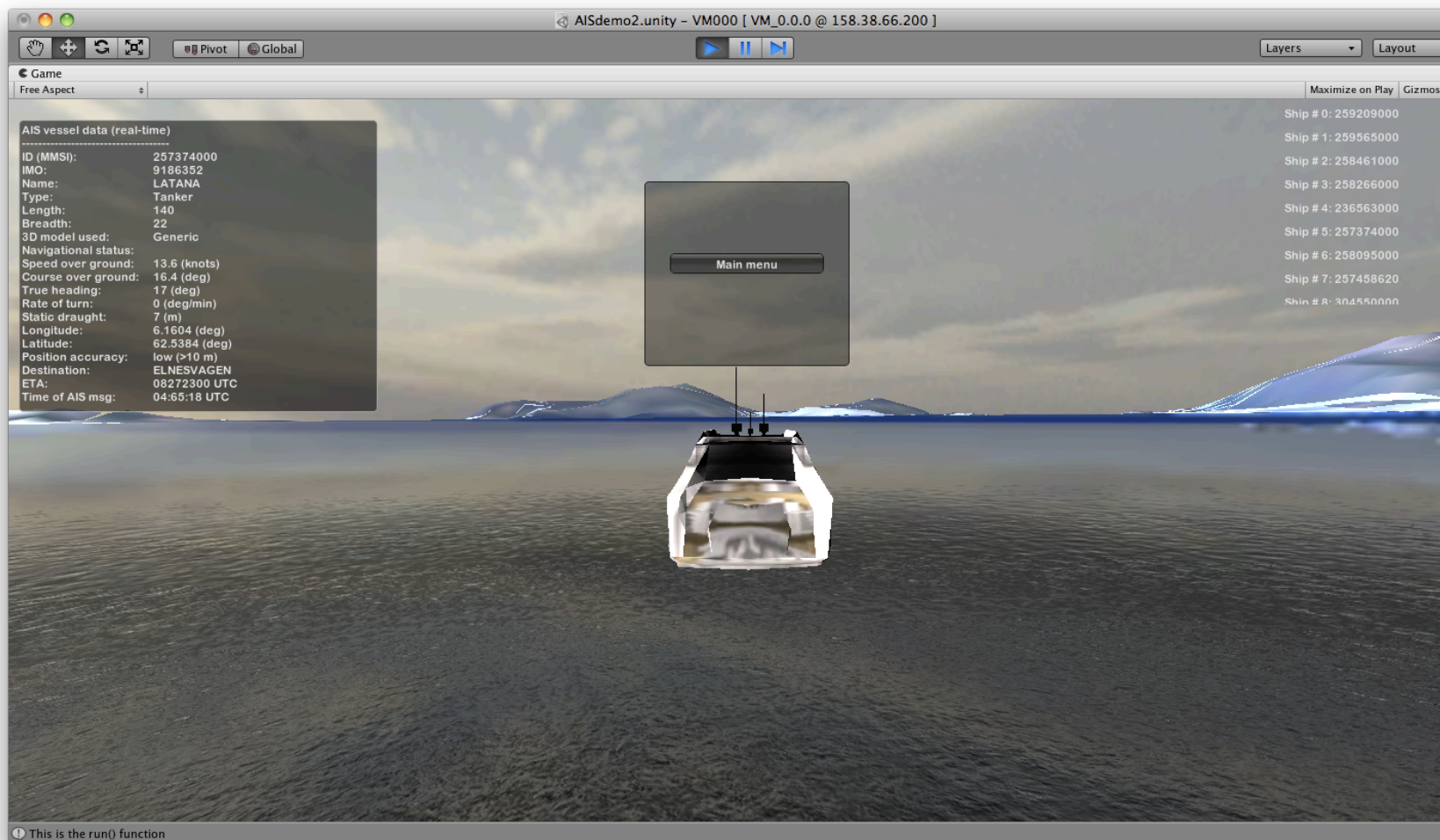
Car agents in a tube tunnel

A car as and agent, carries a camera



Ship agents in action

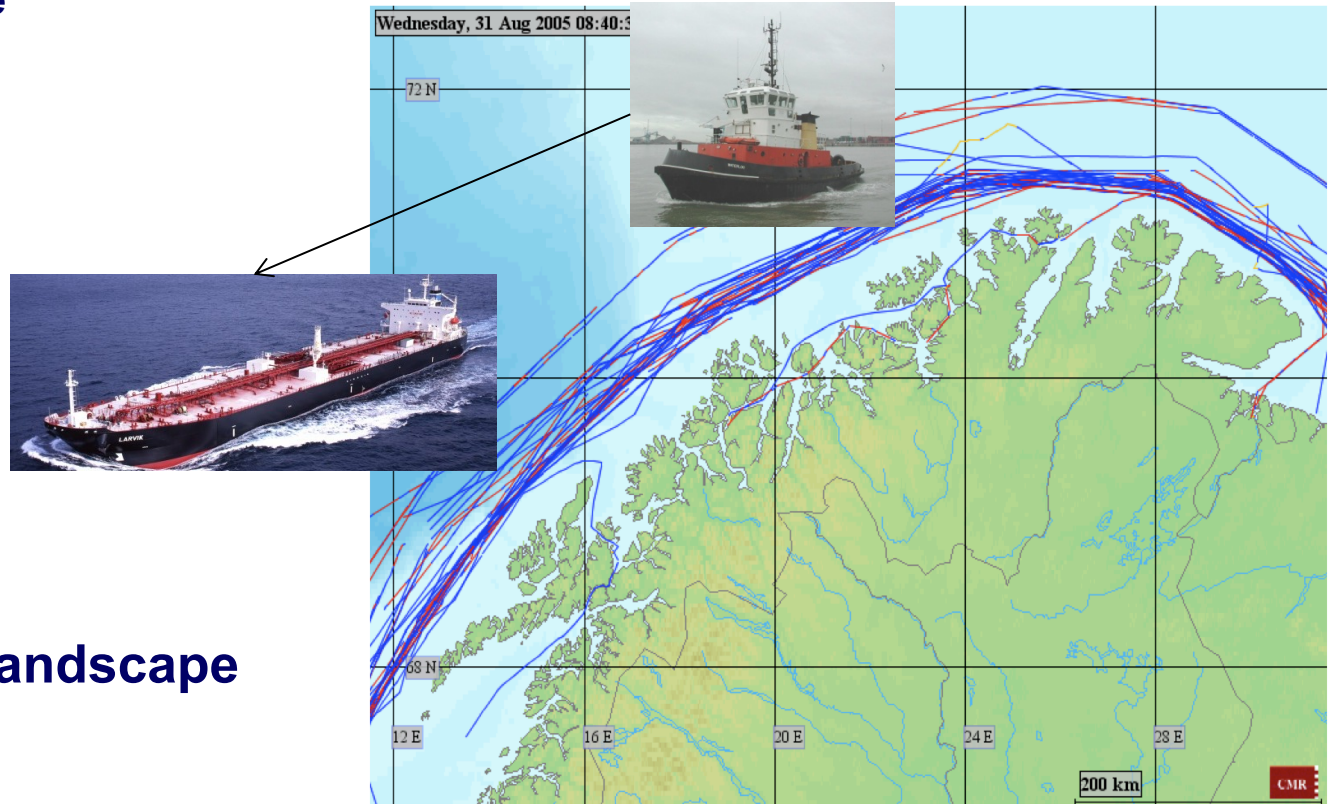
Optimum: speed, road map, energy, cost, safety, service, in real time



Ship agents in action

Ship agents computes the optimum Tanker-Tug position

Oil tanker is a risk at the
Norwegian coastline



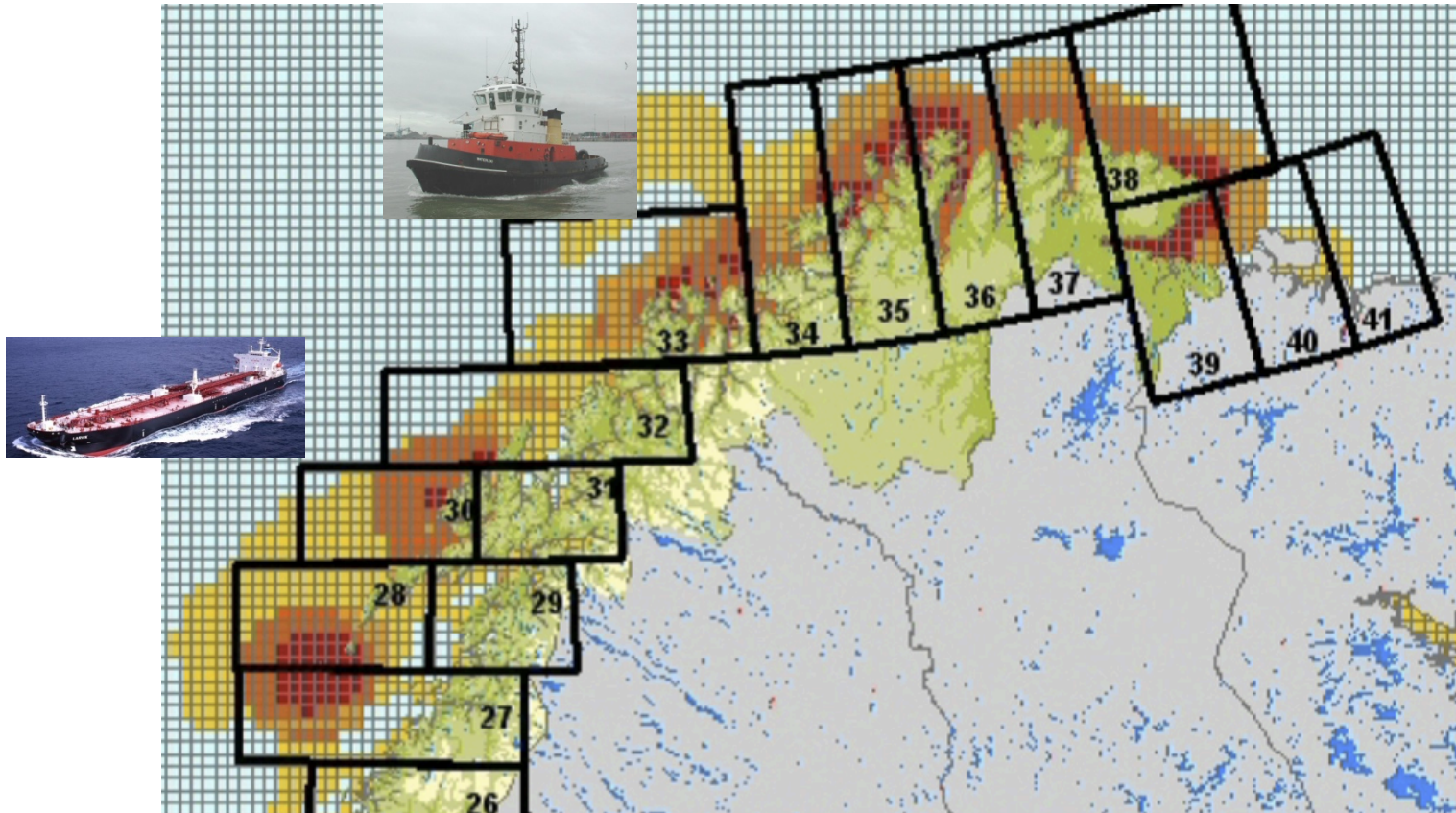
Case Stationary landscape

A general solution

Ship agents in action

Ship agents computes the optimum Tanker-Tug position

Case: Time variant landscape



A position dependent solution

The agent has to recompute an optimum solution

Multi-Agents as fish farmers

System of systems: A swarm of fish farms in Norwegian fjords

Set of fish farm agents

- Related to a real fish farm by a GPS positions
- Economy related to a real fish farm

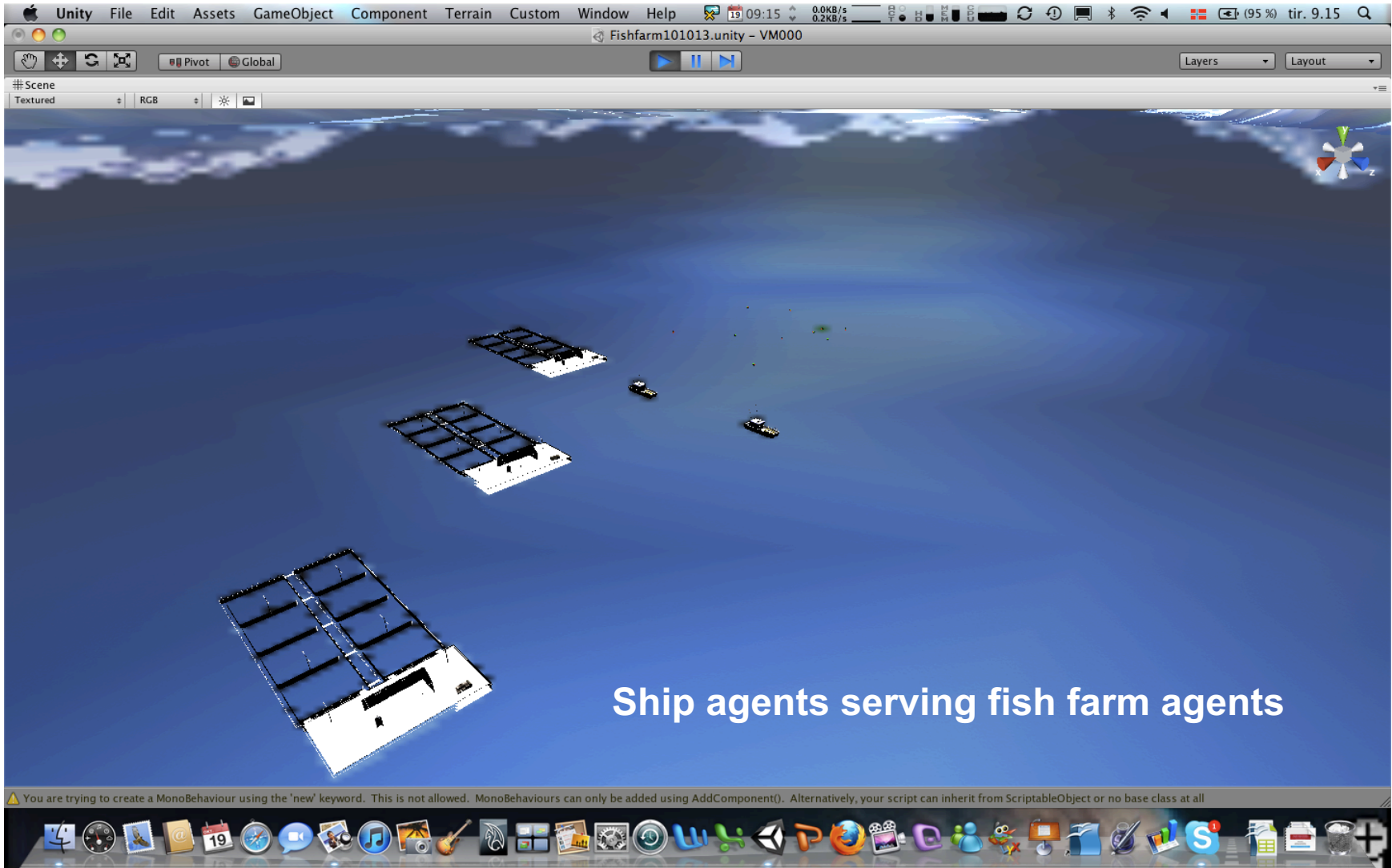
Question

- Is this an optimum position?
- Is this an optimum management



Multi-Agents as fish farmers

Horizontal integration: Fish farm agents and ship agents



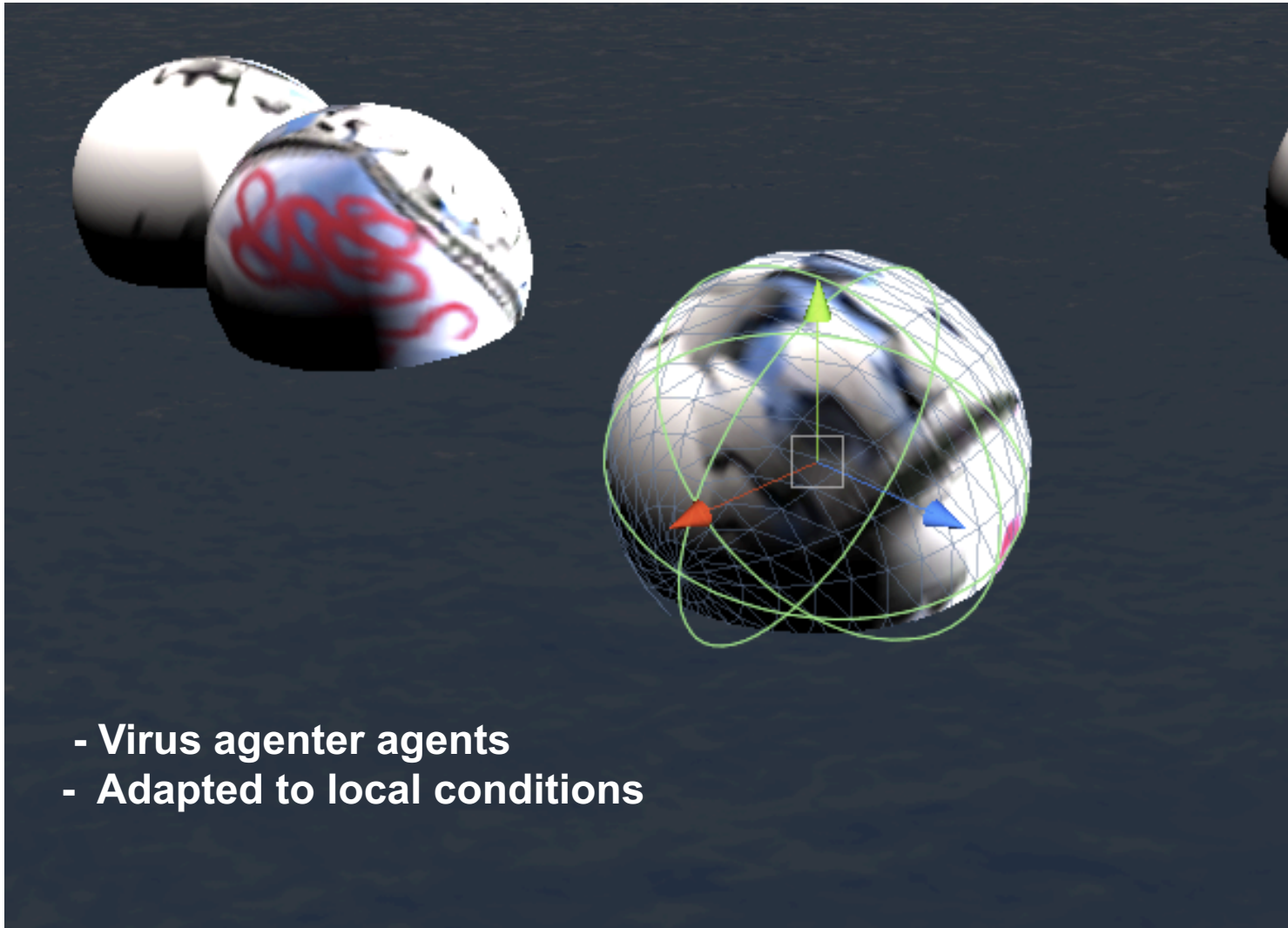
Multi-Agents as fish farmers

System of systems: Fish farm agents, fish agents and virus agents



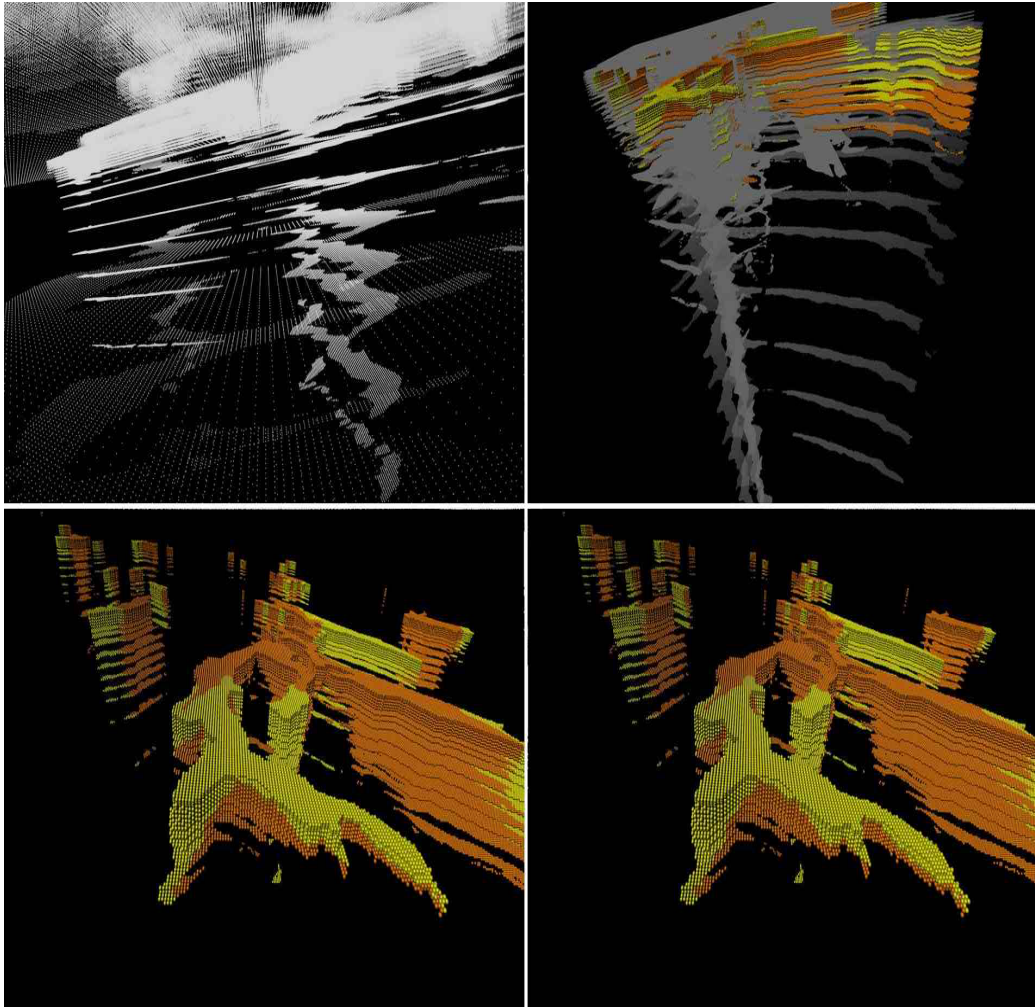
Multi-Agents as fish farmers

Systems to landscape: Virus agents are related to an ocean system



Ocean currents is landscapes

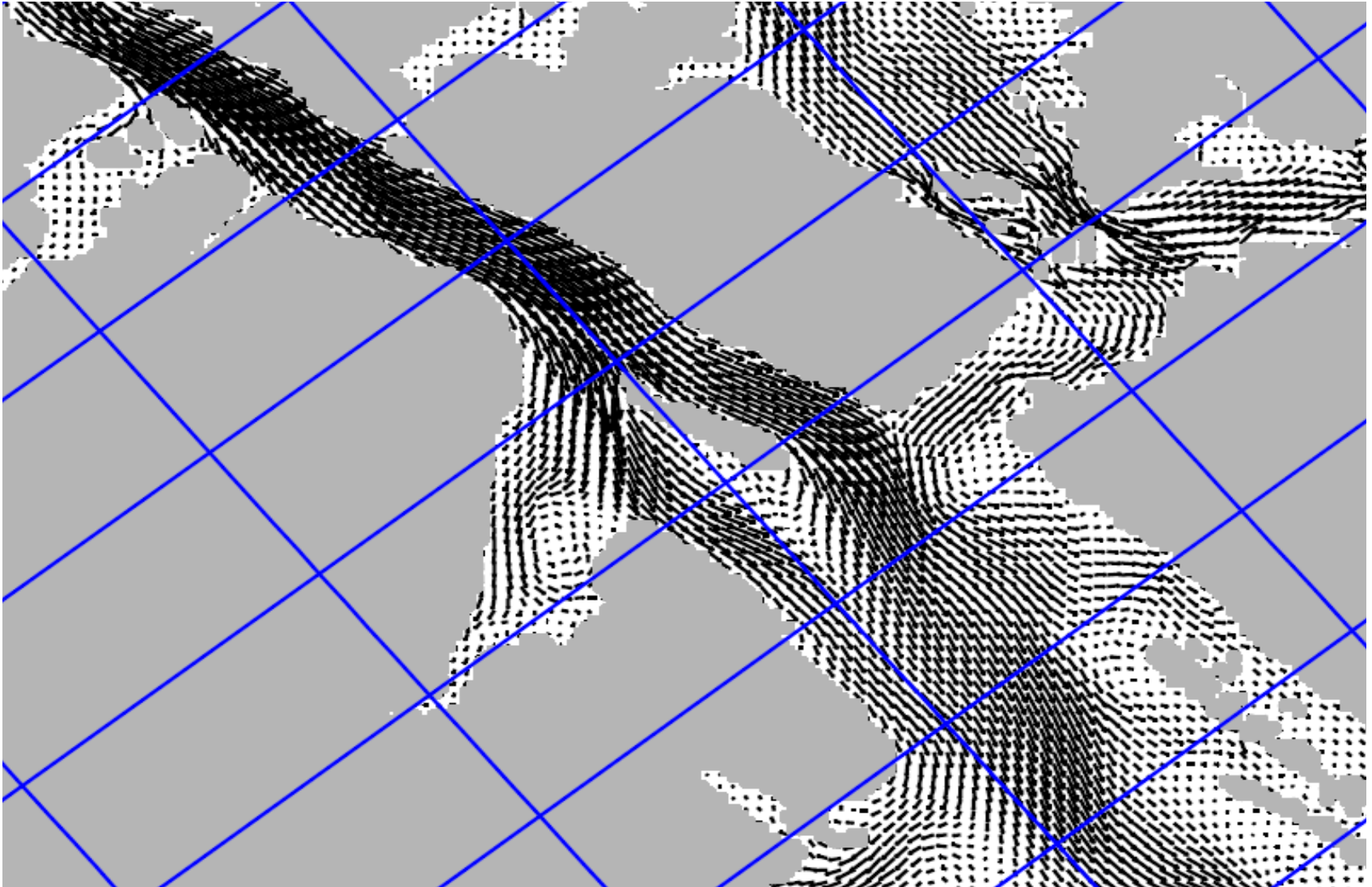
Systems of landscapes: Active virus agents behave different at different temperatures and salinity in the sea



Temperatures are landscapes
Active virus agents in landscape

Ocean currents is landscapes

System of systems: Virus swarm paints produces landscapes



What bringing life to agents?

As a summery



Landscapes

Generic Agents and landscapes concept

- 1 Everything is Agent or landscapes
- 2 Adaptive Agents in landscapes
- 3 Social agents learning
- 4 Evolution agents learning
- 5 Time variant landscapes
- 6 Abstract landscapes as cost functions
- 7 Complex systems dynamics
- 8 Systems of systems

Cost function landscapes

Oceanographic landscape

Climate landscape model

Tide model

Terrain landscape

Astronomy model

Future challenges

Next Virtual More :

- 1 Big agent swarms > 1 million
- 2 Parallel computing
- 3 Generic agent modeling
- 4 Time variant landscapes
- 5 Abstract landscapes as cost functions
- 6 Complex systems dynamics



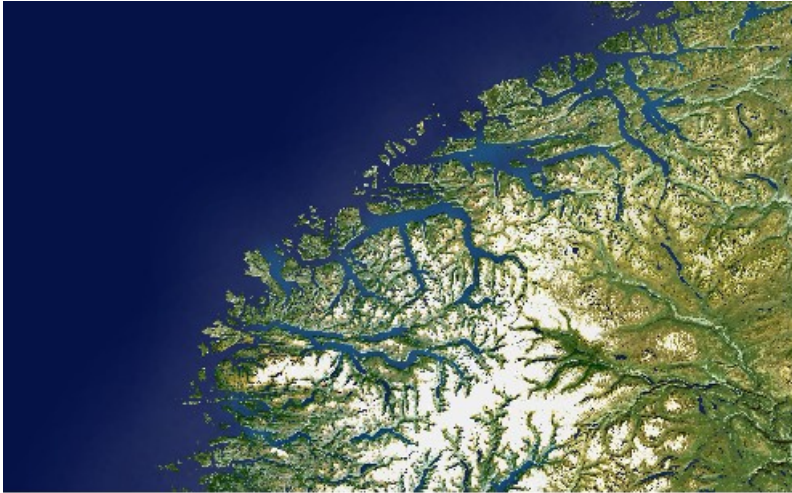
Thank you

More information?

You will find me, at the end of the rainbow

<http://ansatte.hials.no/hy/>

3D terrain model challenges



1. Integration of large 3D terrain and sea maps
2. Position resolution and accuracy
3. Communication between 3D maps and agents
4. Computer capacity

The Map as a research arena

Needs a paradigm shift in simulation methods



From deterministic Newton dynamics



To individual modeling, based on free will

